

CSE 350

Advanced Data Structures

Topic 10: Hash-Based Storage 📦🕒#

Review: Modular Arithmetic

0	1	2	3	4	5	6	7
0	1	2	3	4	5	6	7
8	9	10	11	12	13	14	15
16	17	18	19	20	21	22	23

Review: Hash Functions

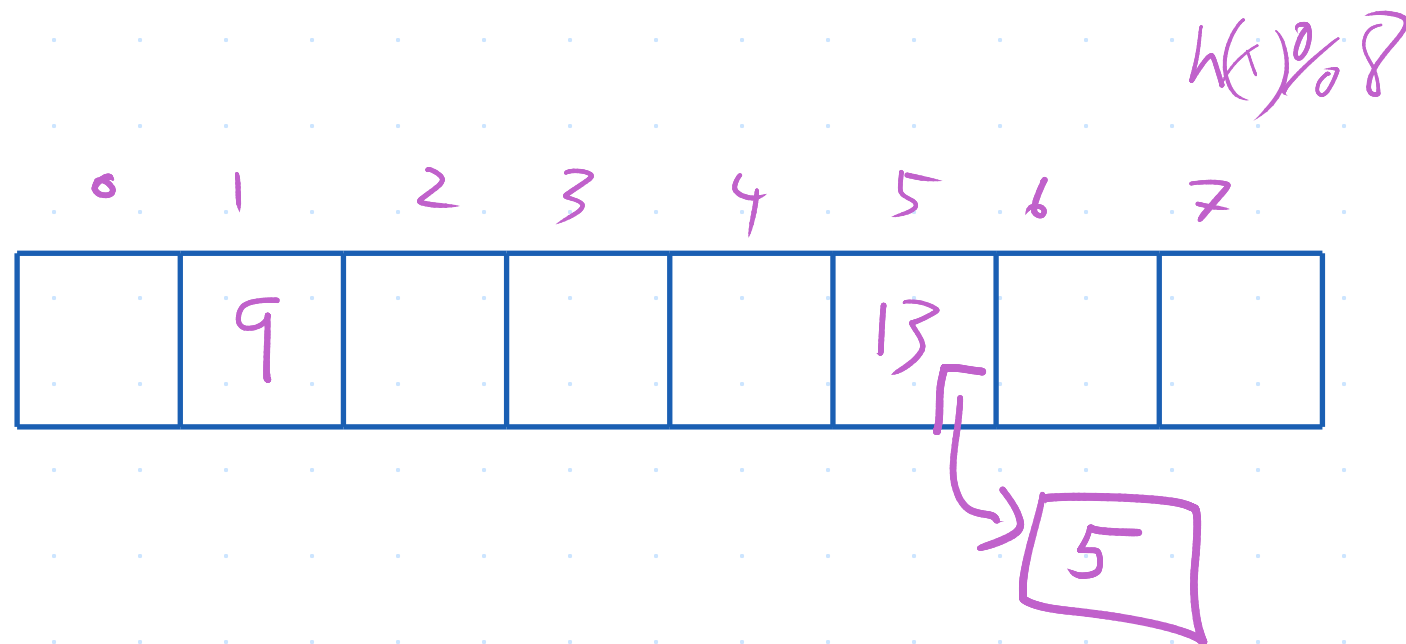
Examples
SHA256
MD5
BCrypt
MurmurHash3

$h(x)$ → Pseudo random, uniform over $[0, \text{Max}]$
→ Deterministic: $h(x) = h(x) = h(x)$
→ Statistically independent $h(x) \neq h(x')$ for $x \neq x'$
↑ any sequence of bits
Hash function

$h(x) \bmod N$ has the same properties
" $h(x) \% N$ " (if $N \ll \text{Max}$)

Review: Hash Tables

$$\text{ex: } h(x) = x$$



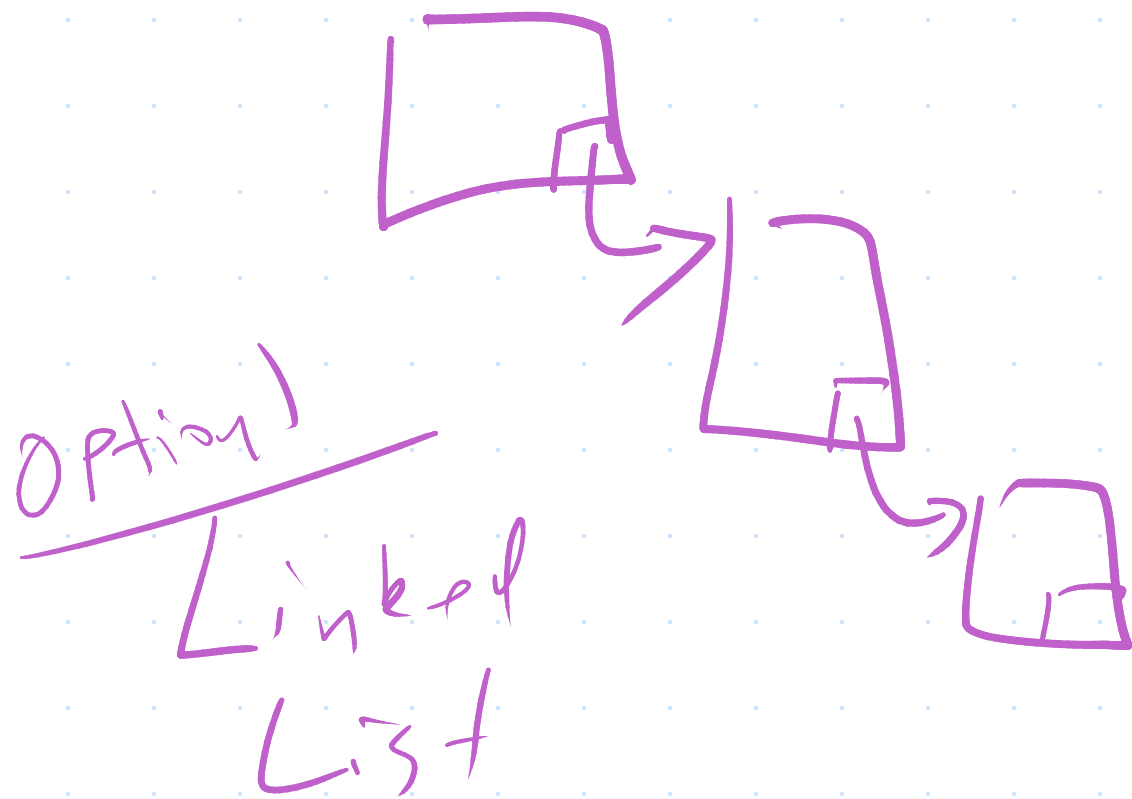
Expected number of items in each bucket

N = Number of Records

B = Number of Buckets

$$E[\text{records}] = \frac{N}{B}$$

What happens if the buckets overflow?



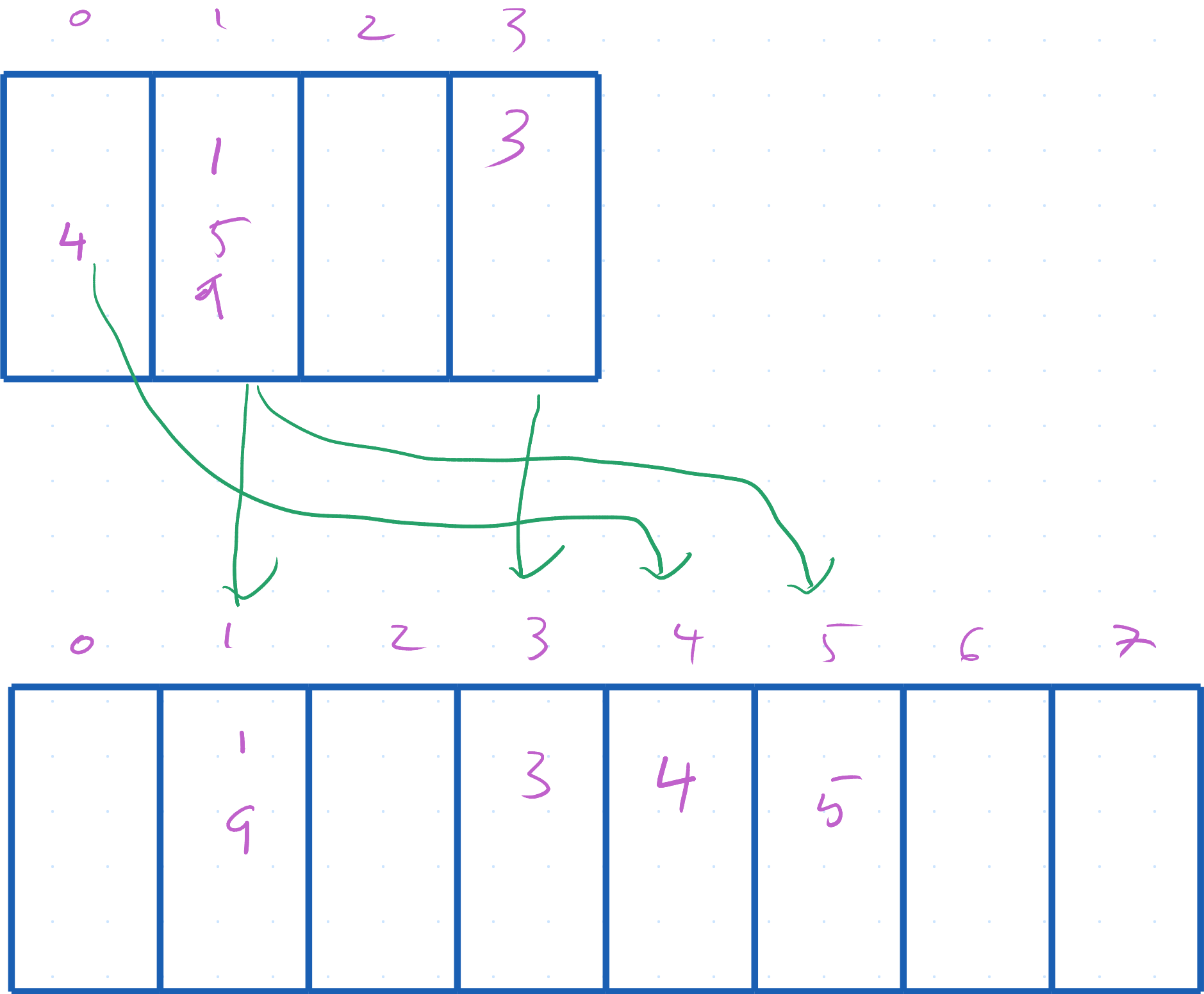
Option 2

resize to $2 \times$ original size
(Amortizes to $O(1)$ per insert)

What changes when we store buckets on disk?

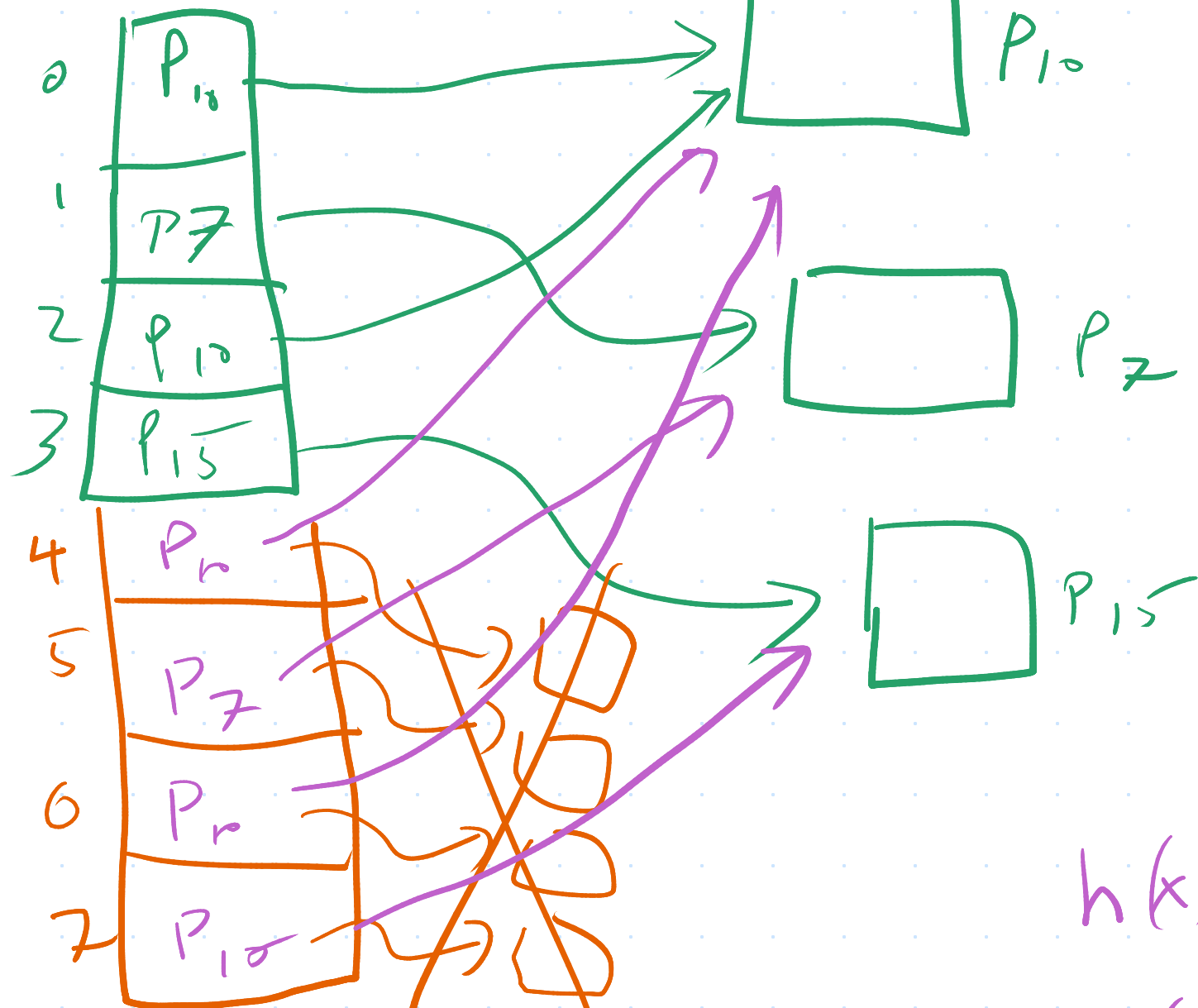
- We like spatial locality: Make $\frac{N}{B} \approx P$
We want $\sim P$ records
per bucket
still one IO to
fetch all
- Resizing Becomes Super Extensive
↳ Read Entire Hash Table & Write it Back

Resizing the Hash Table



Dynamic Hashing

Directory



To grow directory,
append a copy
of the existing
directory

$$h(x) \% N = i \rightarrow h(x) \% 2N = i + N$$

$$h(x) \% 2N = i$$

Each data page goes to
one of two new data
pages

In memory
(or Buffer M_1)

Extras

Track - directory depth (D)

Directory has 2^D entries

- data page depth (d)

→ Data page stores records
that hash to
 $h(x) \% 2^d = \bar{i}$

If data page fills up

↳ $d = D$?

↳ Double directory size

↳ create new page for $h(x) = \bar{i} + 2^d$ @ depth $d+1$

↳ increase page depth to $d+1$

↳ rehash the page

Con

- more complicated
- Less spatial locality

Pro

- No "big" resize events
 - ↳ work more spread out
 - ↳ more resilient to bad hash fn

Hash Partitioning: Aggregation

group-by aggregation → Need memory to hold each group



~~①~~ → ~~2~~ → write to disk
②

~~b~~ → ~~3~~ → write to disk
③

④ →

Example

2 groups

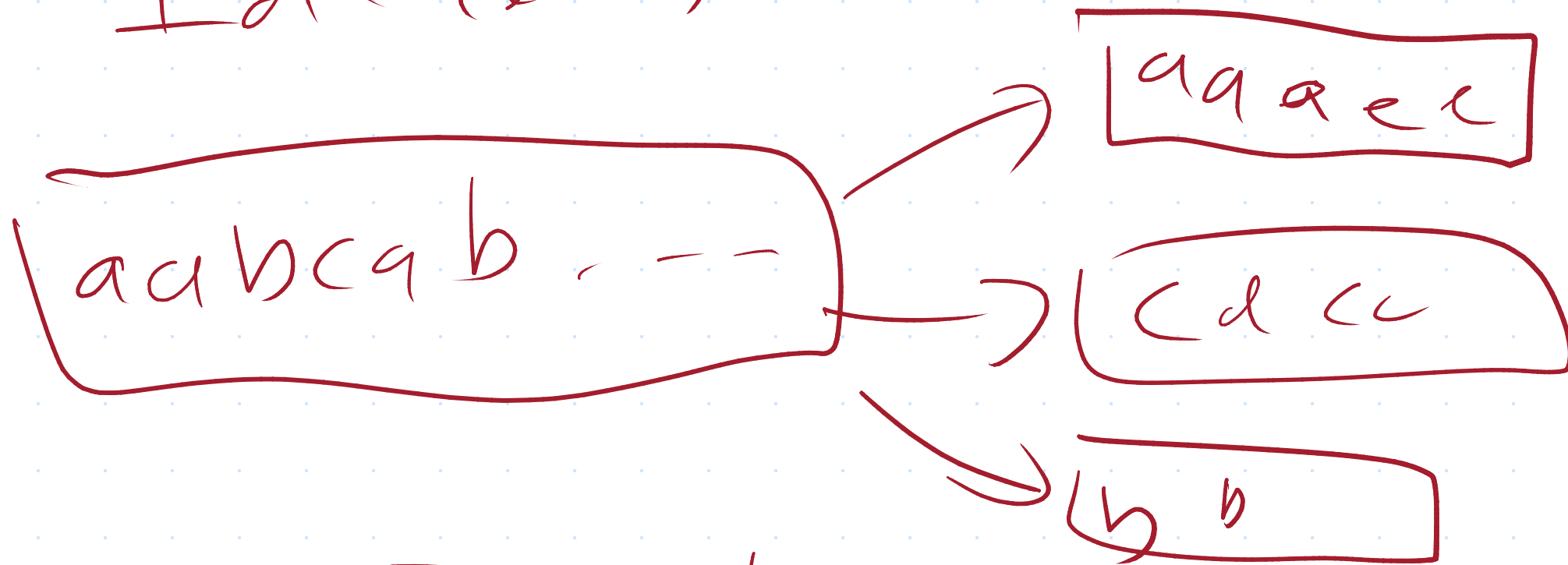
3 records

} memory size

read a → ~~3~~
⑤

If not enough space for all groups
you (usually) get random access

Idea: use hash to partition



Pick B so that
each partition is very likely
to fit in memory!

1. Read input a little at a time
($O(N)$ I/Os)

2. Keep one file open per partition
append records to the right file
($O(N)$ I/Os)

3. Reread each partition file
one at a time
 $O(N)$ I/Os

$\sim 3N$ I/Os