

CSE 410: Midterm Review

March 1, 2024

Exam Day

- **Do** have...
 - Writing implement (pen or pencil)
 - One note sheet (up to $8\frac{1}{2} \times 11$ inches, double-sided)
- You will **not** need...
 - Computer/Calculator/Watch/etc...

Abstract Disk API

- **Disk** : A collection of **Files**
- **File** : A list of pages, each of size P ($\sim 4K$)
 - `file.read_page(page)`: Get the data on page `page` of the file.
 - `file.write_page(page, data)`: Write data to page `page` of the file.

of calls = IO complexity

Complexity

```
1  const RECORDS_PER_PAGE = sizeof::<Record>() / PAGE_SIZE;
2
3  fn get_element(file: File, position: u32) -> Record
4  {
5      let page = position / RECORDS_PER_PAGE;
6      let data = file.read_page(page);
7      return get_records(data)[position % RECORDS_PER_PAGE];
8  }
```

$O(1)$ memory

— memory complexity $O(1)$
— IO complexity $O(1)$

Complexity

```

1  fn find_element(file: File, key: u32) -> Record
2  {
3      let mut records: Vec<Record> = Vec::new()
4      for page in (0..N)
5      {
6          let data = file.read_page(idx);
7          for record in get_records(data)
8          {
9              records.push(record);
10         }
11     }
12     return records.binary_search(key)
13 }

```

+ IO

mem

$O(N)$ IO

$O(N)$ mem

↳ p is a constant

Streaming Reads/Writes

```
1 struct BufferedFile {
2     file: File,
3     buffer: Page,
4     page_idx: u32,
5     record_idx: u16,
6 }
7 impl BufferedFile {
8     fn append(&mut self, record: Record) {
9         self.buffer[self.record_idx] = record;
10        self.record_idx ++;
11        if self.record_idx >= RECORDS_PER_PAGE {
12            self.file.write_page(self.page_idx, self.buffer);
13            self.record_idx = 0; self.page_idx ++;
14        }
15    }
16 }
```

O(N) IOs
O(1) memory

Streaming Reads/Writes

```

1  struct BufferedFile {
2      file: File,
3      buffer: Page,
4      page_idx: u32,
5      record_idx: u16,
6  }
7  impl BufferedFile {
8      fn next(&mut self) -> Record {
9          if self.record_idx >= RECORDS_PER_PAGE {
10             self.file.read_page(self.page_idx)
11             self.page_idx += 1; self.record_idx = 0
12         }
13         self.record_idx += 1
14         return self.buffer[self.record_idx - 1];
15     }
16     ...
17 }

```

$O(N)$ IOs $\rightarrow N$ records
 $O(1)$ Mem

Complexity

```

1  fn group_by_sum(input: BufferedFile, output: BufferedFile) {
2      let mut buffers: Vec<BufferedFile> = Vec::new();
3      for _i in (0..B) { buffers.push(BufferedFile::new()); }
4      while !input.done() {
5          let record = input.next();
6          let i = HASH(record.key) % B;
7          buffers[i].append(record)
8      }
9      for i in (0..B) {
10         let local_sums: Map<String, f32> = Map::new();
11         buffer[i].reset()
12         while !buffer[i].done() {
13             let record = buffer[i].next();
14             local_sums[record.key] += record.value;
15         }
16         for key, value in local_sums {
17             output.append(Record { key, value } )
18         }
19     }
20 }

```

Records

$\frac{N}{B}$ $O(1)$
 B $O(N)$ IO

B
 $\frac{N}{B}$ $O(1)$ IO

N times

B buffer files

O(1)

O(B)

O(1) IO

N times

O(N)

IOs

Total of $\frac{N}{B}$ groups

groups total

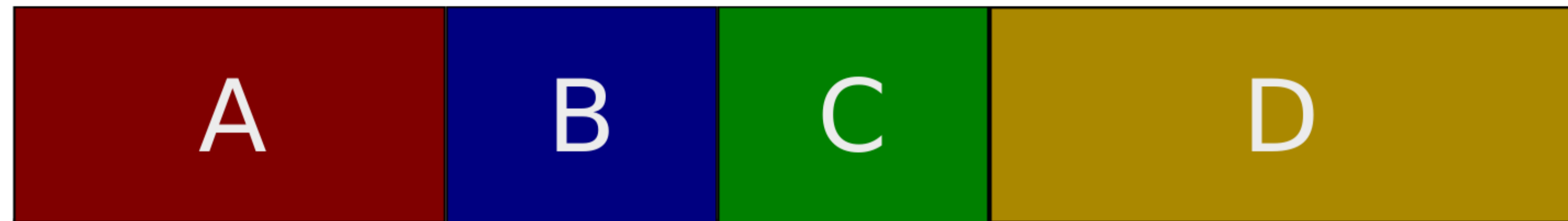
O(1) IO

$$\frac{max}{O(A) + O\left(\frac{G}{B}\right)} = O\left(\frac{G}{B}\right)$$

$$\frac{I^0}{\underbrace{O(N) + O\left(\frac{N}{B} \cdot B\right)}_{O(N)} + \underbrace{O\left(\frac{G}{B} \cdot B\right)}_{O(G)}} = O(N)$$

$C < B$

Record Layouts

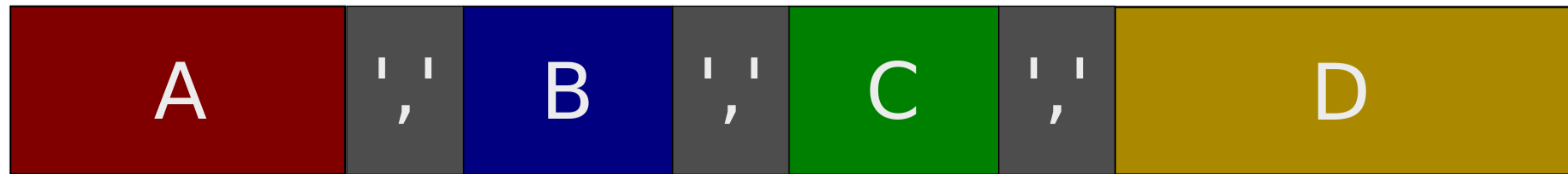


Base Address (X)

Address of C ($X + |A| + |B|$)

const time lookup

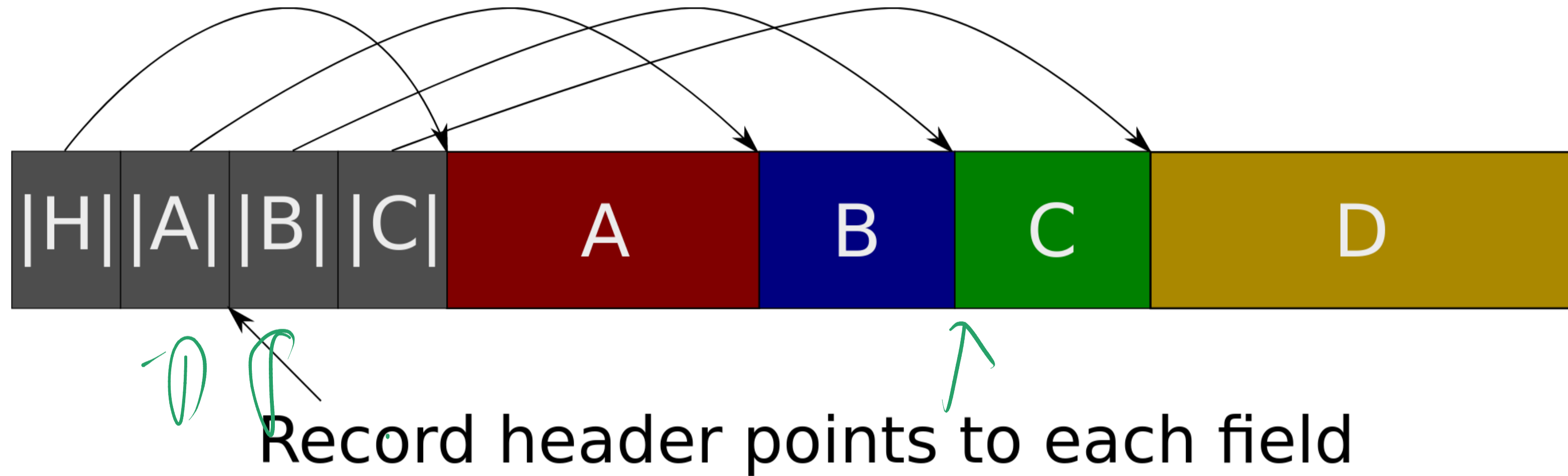
Record Layouts



Special Separator Characters Delimit Fields

Ref: d, reys dij .time

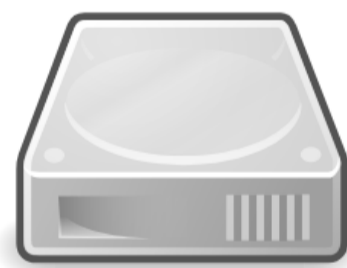
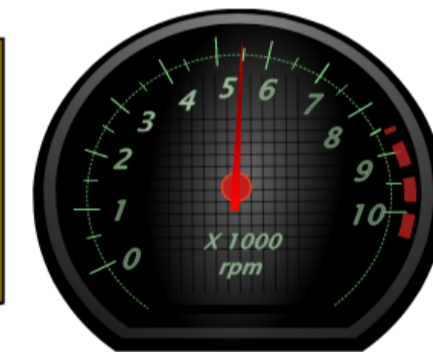
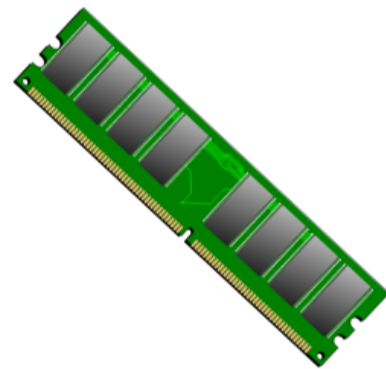
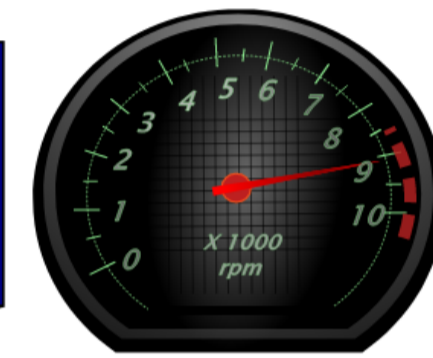
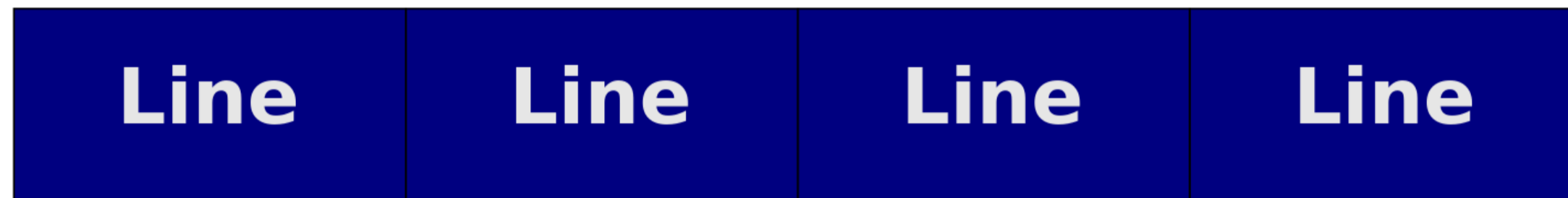
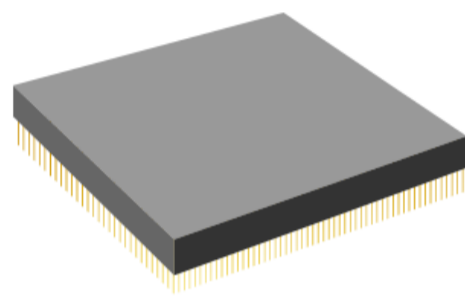
Record Layouts



Record Layouts

- **Fixed:** Constant-size fields. Field i at byte $\sum_{j < i} |Field_j|$.
- **Delimited:** Special character or string (e.g., ,) between fields.
- **Indexed:** Fixed-size header points to start of each field.

Page Layouts

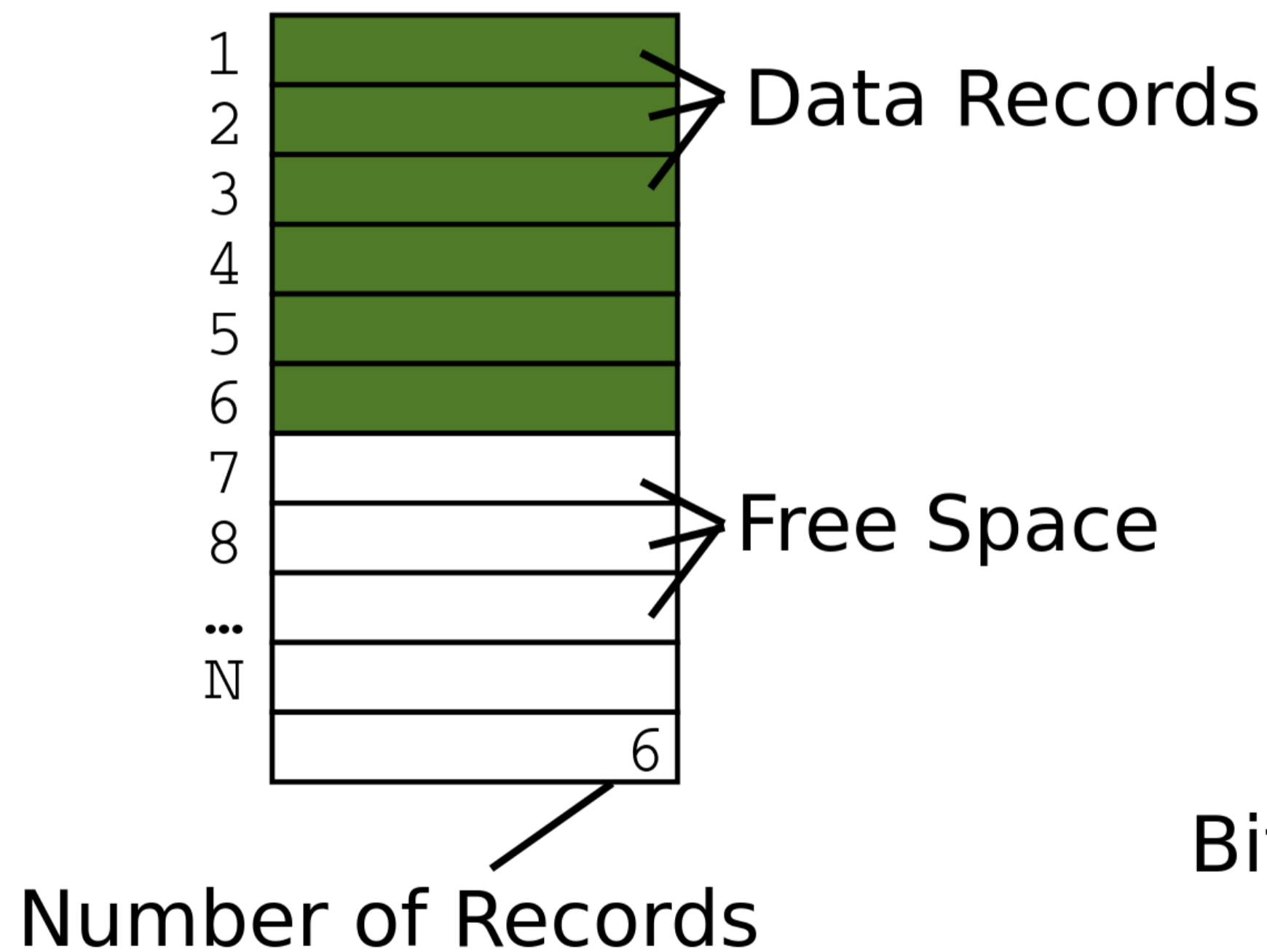


Page Layouts

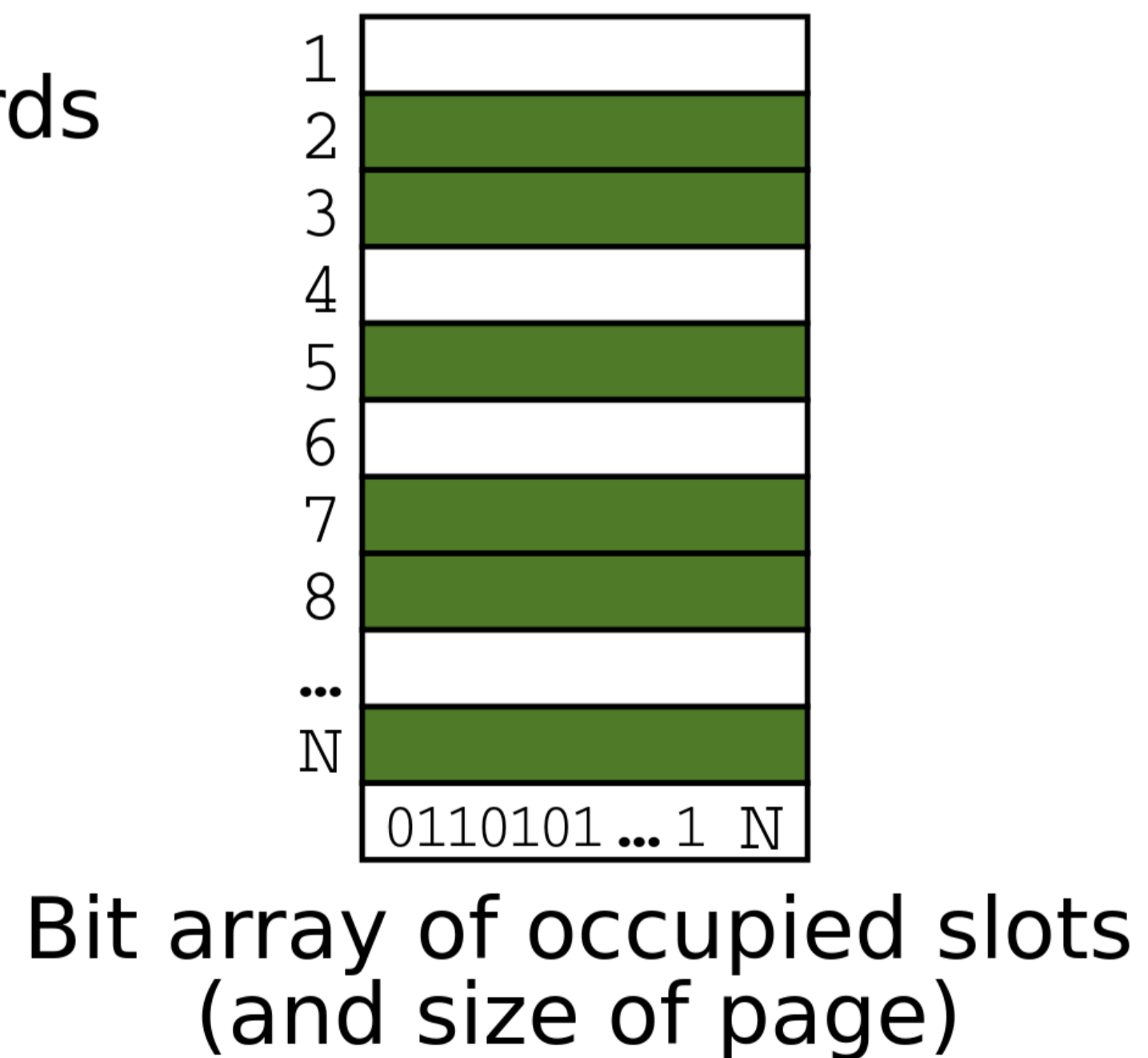
- **Fixed:** Constant-size records. Record i at byte $i \cdot |Record|$.
- **Delimited:** Special character or string (e.g., `\n`) between records.
- **Indexed:** Fixed-size header points to start of each record.

Page Layouts

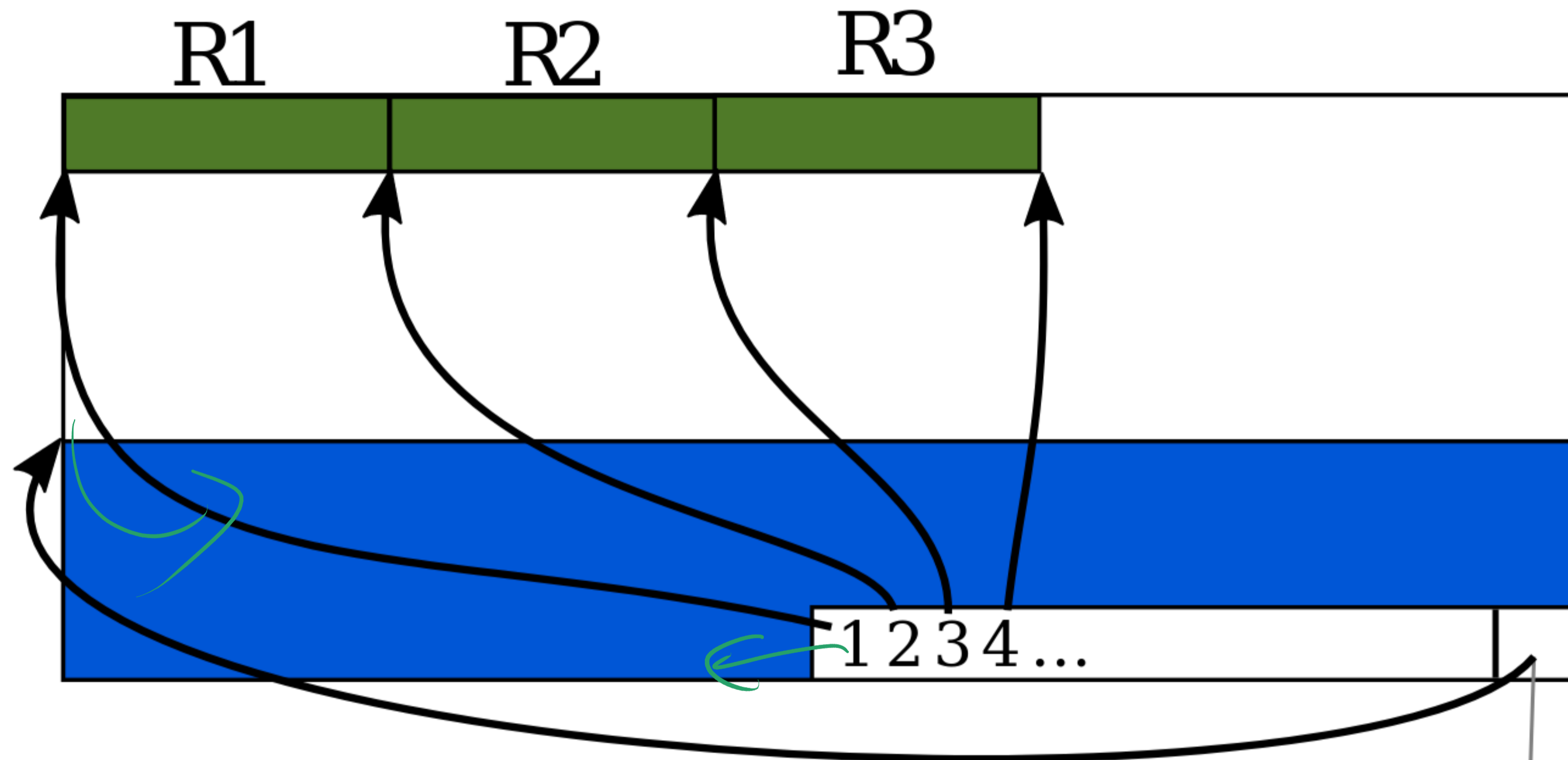
Packed



Unpacked (Bitmap)

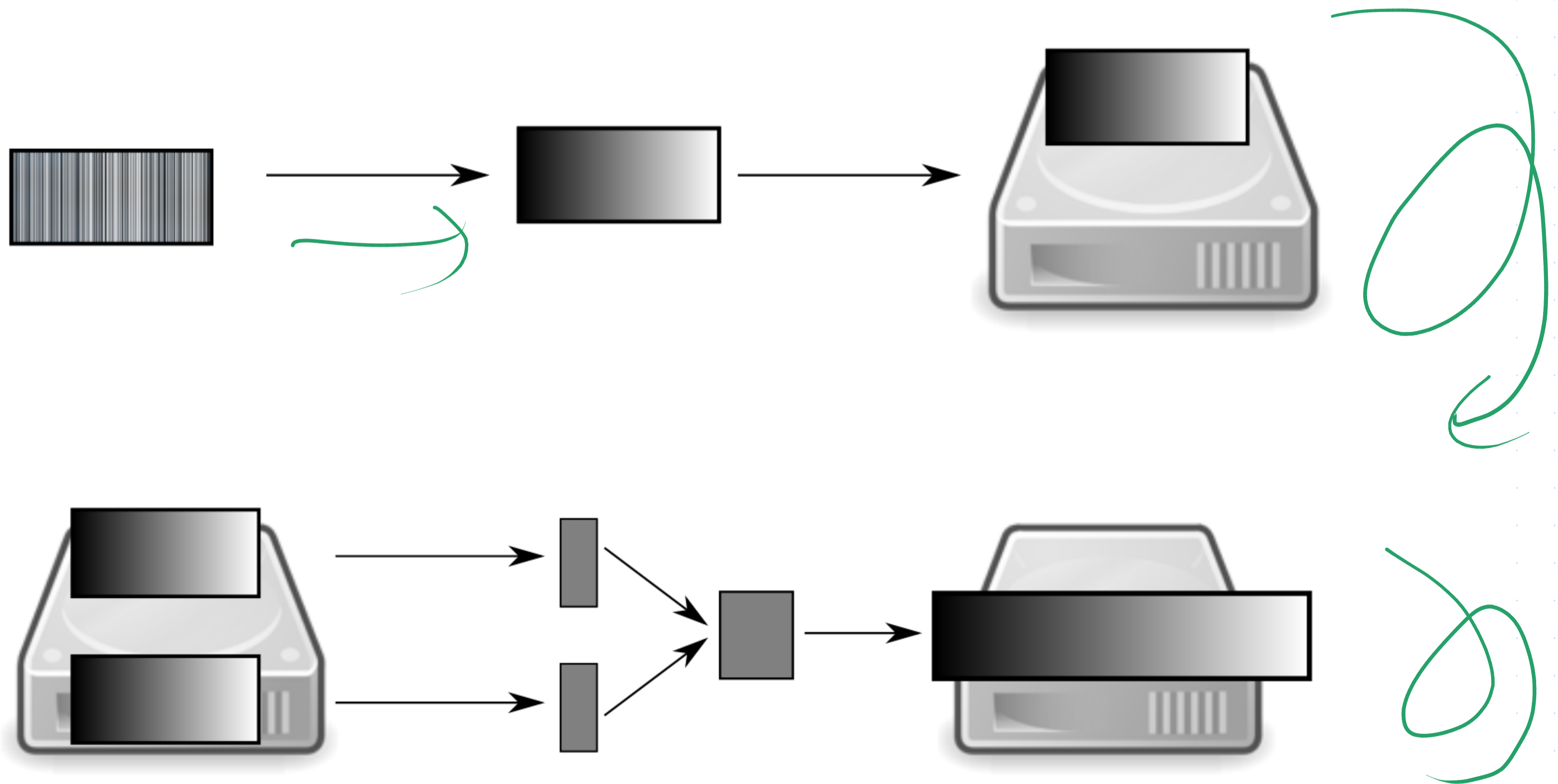


Page Layouts

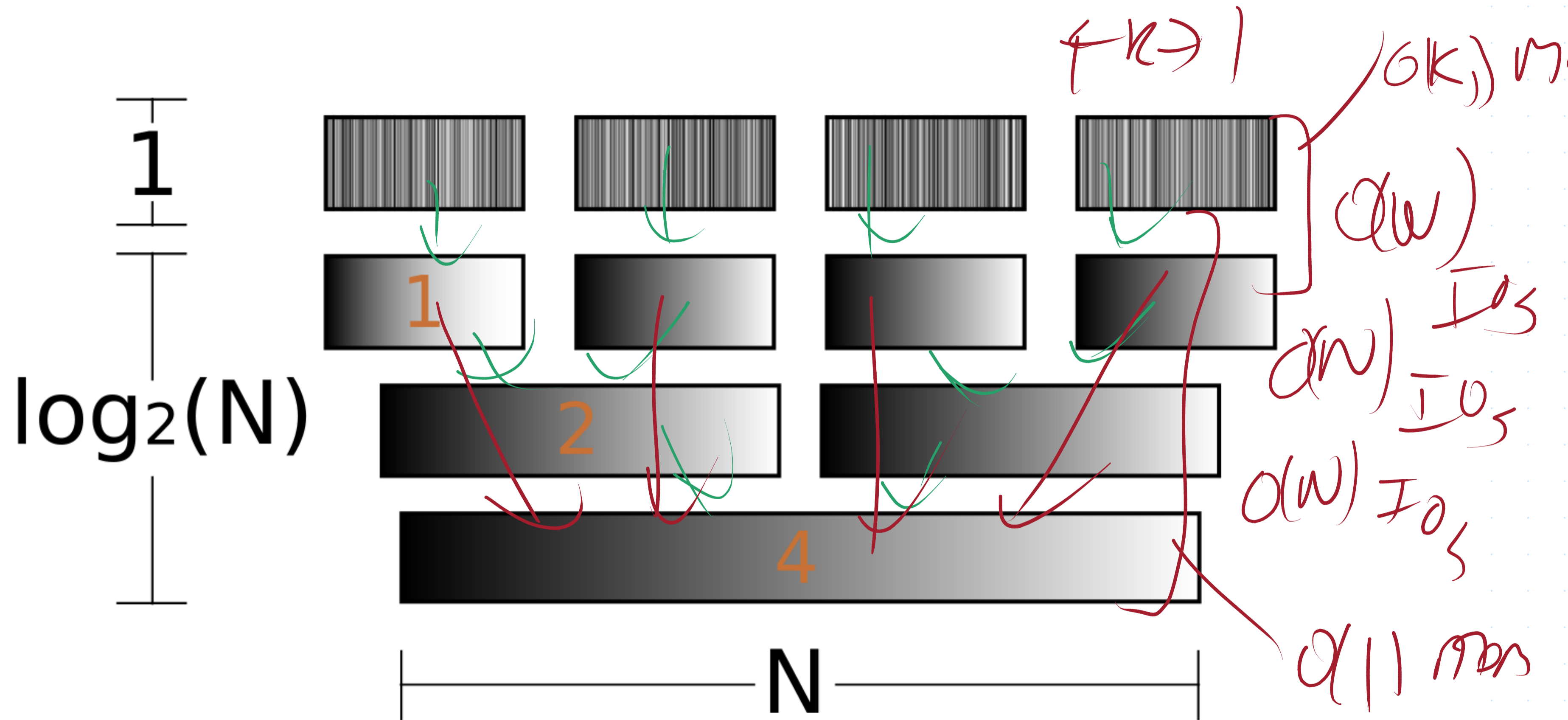


Pointer to start of free space

2-Pass Sort



2-Pass Sort



m

2-Pass Sort

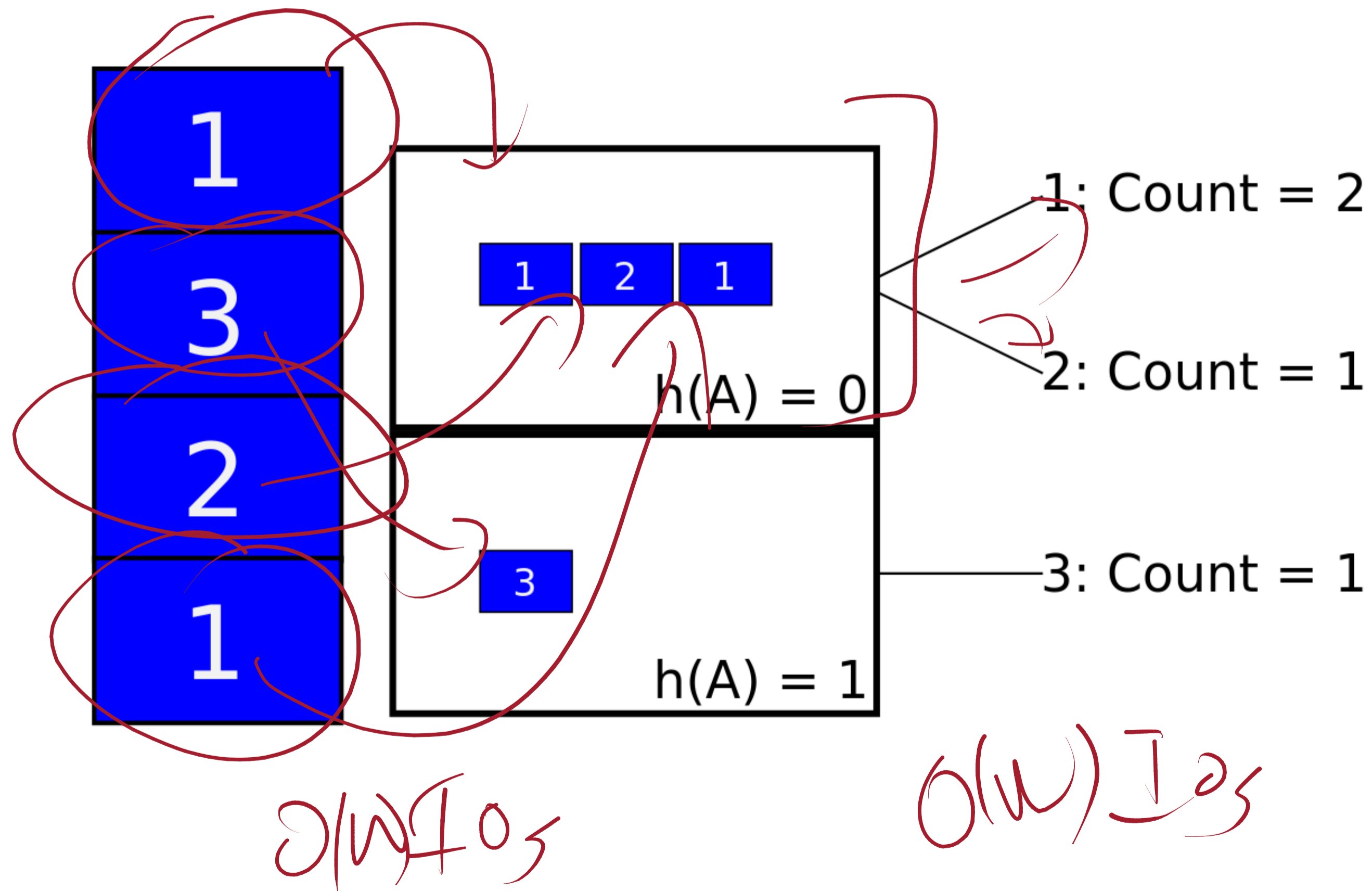
- **Pass 1:** Use $O(K)$ memory for the initial buffer
- **Pass 2:** Merge $O(K)$ buffers simultaneously

Aggregation

TREE_ID	SPC_COMMON	BORONAME	TREE_DBH
---------	------------	----------	----------

180683	'red maple'	'Queens'	3
	{ 'red maple' = 1 }		
204337	'honeylocust'	'Brooklyn'	10
	{ 'red maple' = 1, 'honeylocust' = 1 }		
315986	'pin oak'	'Queens'	21
	{ 'red maple' = 1, 'honeylocust' = 1, 'pin oak' = 1 }		

Aggregation



Aggregation

TREE_ID	SPC_COMMON	BORONAME	TREE_DBH
---------	------------	----------	----------

204337	'honeylocust'	'Brooklyn'	10
--------	---------------	------------	----

{ 'honeylocust' = 1 }

204026	'honeylocust'	'Brooklyn'	3
--------	---------------	------------	---

{ 'honeylocust' = 2 }

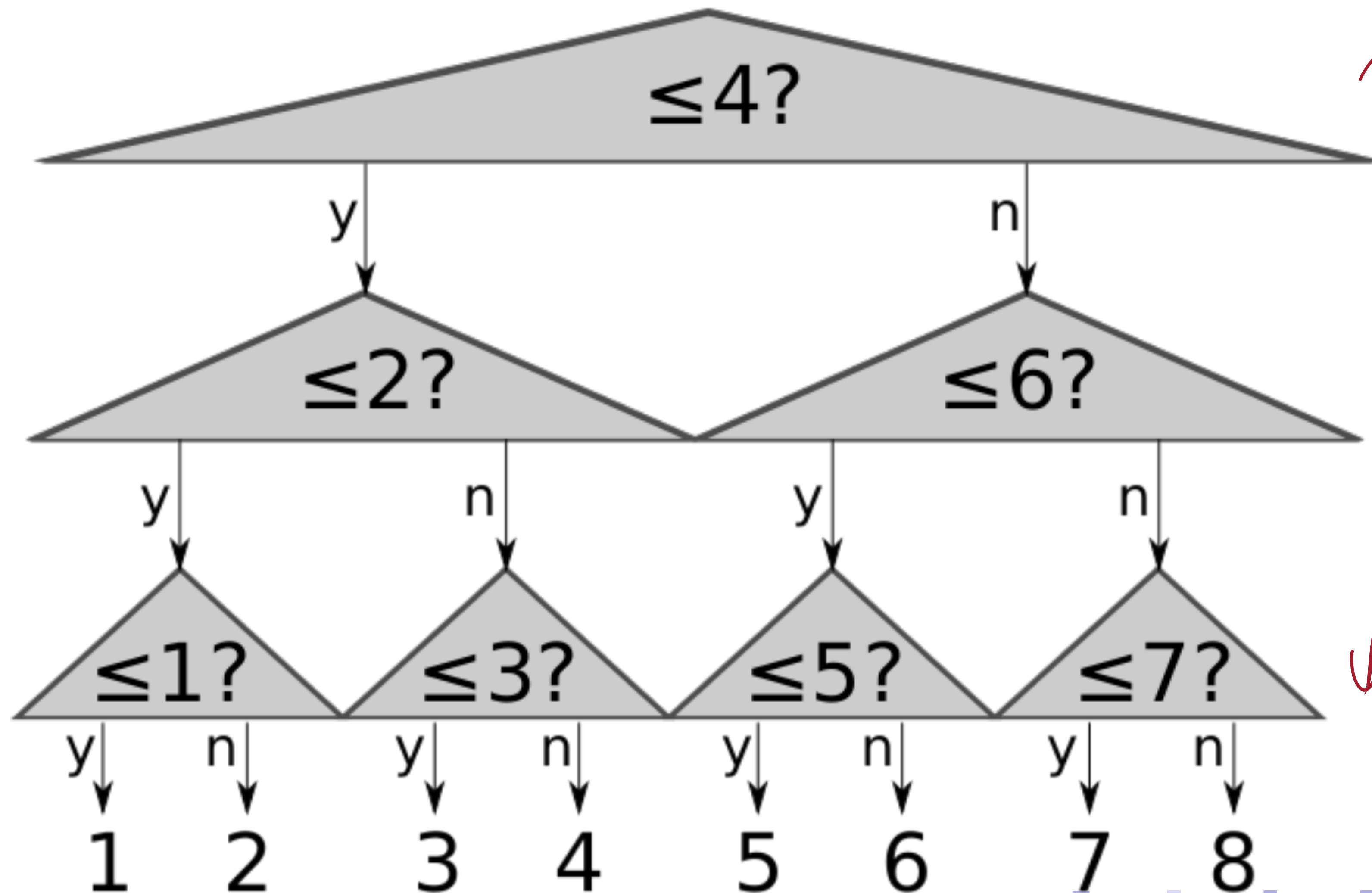
... and more

315986	'pin oak'	'Queens'	21
--------	-----------	----------	----

{ 'honeylocust' = 3206, 'pin oak' = 1 }

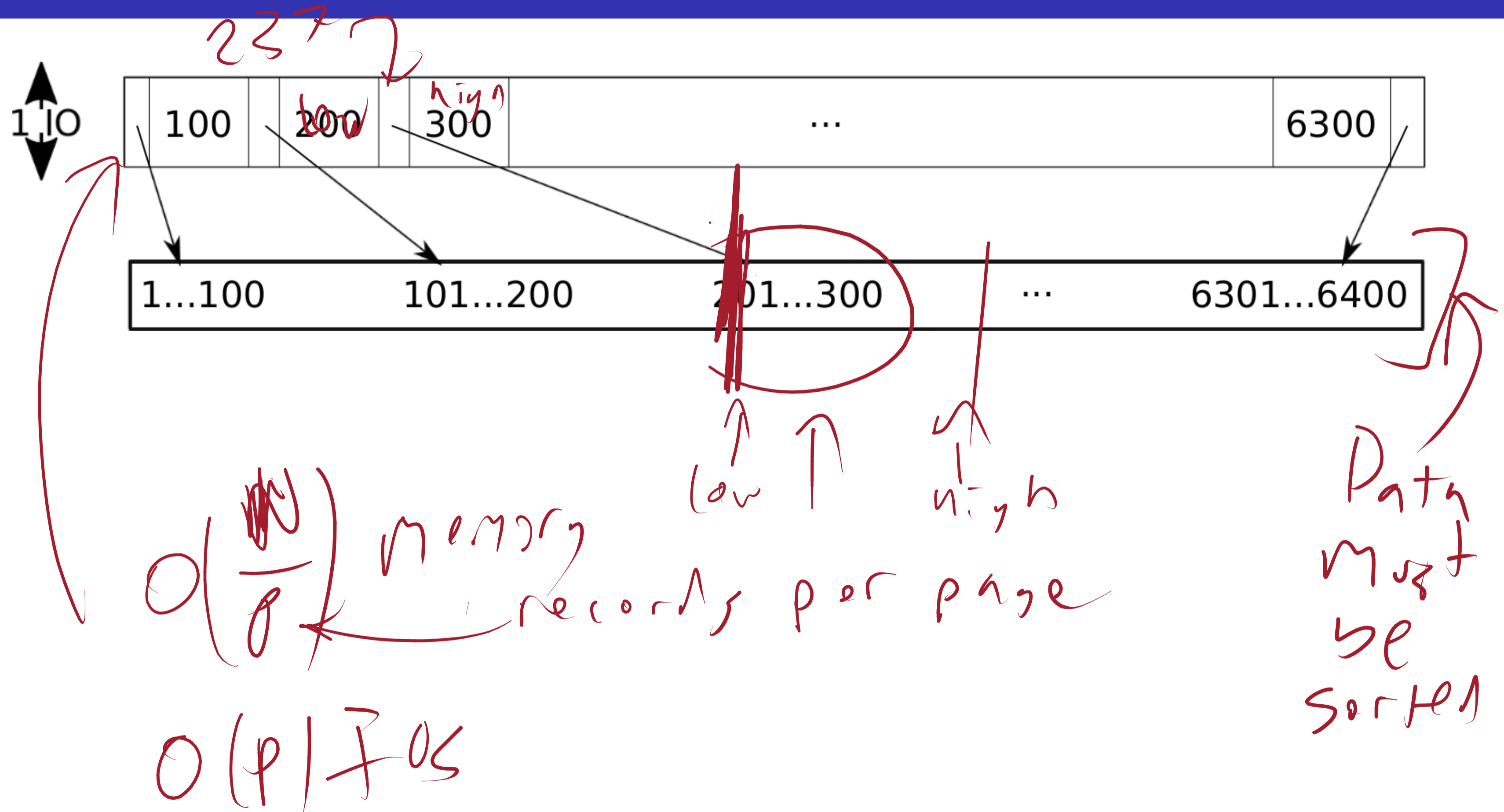
$O(1)$ may
 $O(N)$ reads

Binary Search

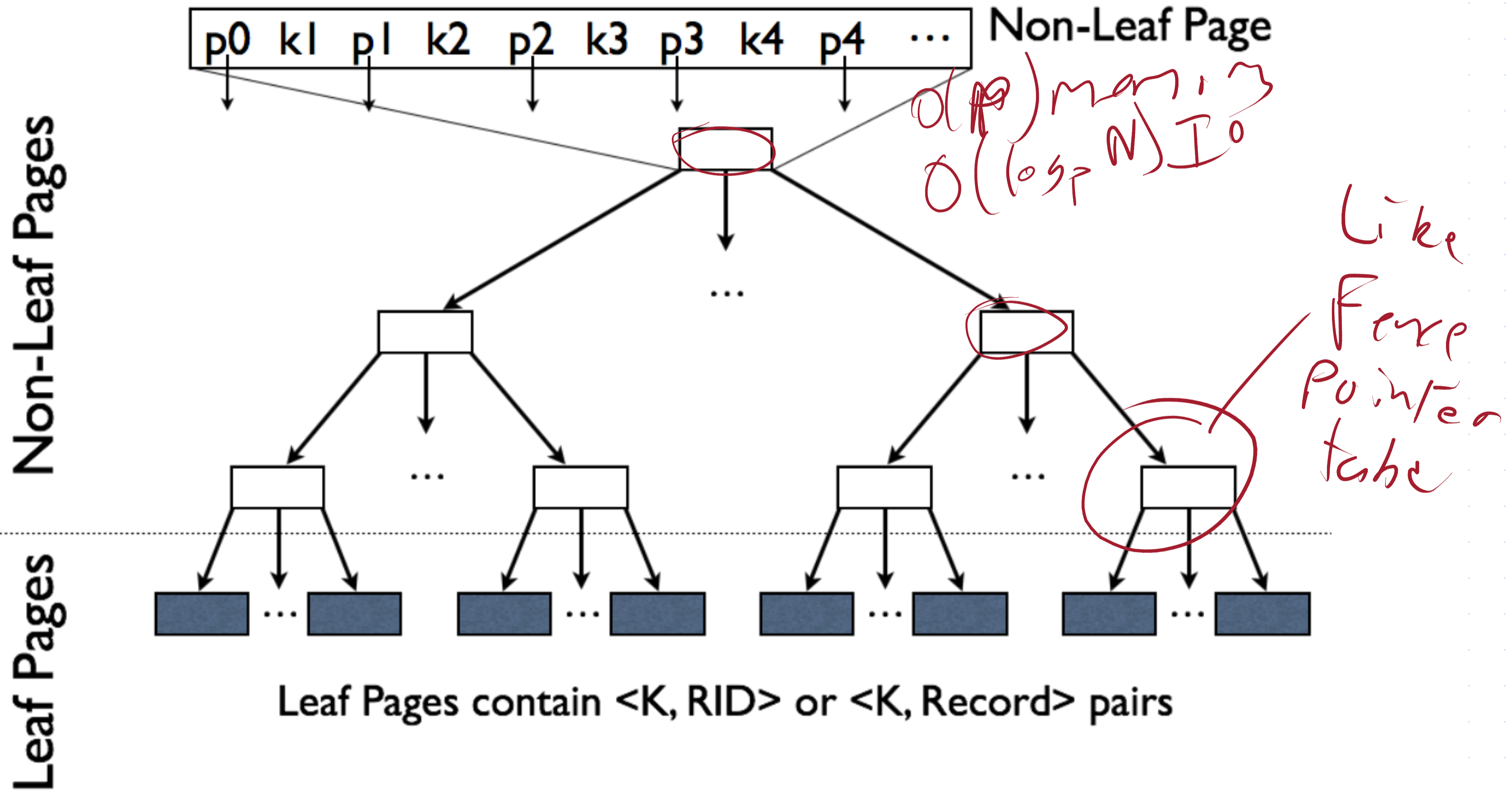


$\Theta(\log_2 N)$

Fence Pointers



ISAM Index



B+ Tree

Like an ISAM index, but not every page needs to be full, and...

Any page (except the root) must be at least half-full

- Splitting a full page creates a half-full page.
- On deleting the $\frac{P}{2}$ th record, steal record from adjacent page.
- If no records can be stolen, must be able to merge with an adjacent page.

$O(P)$ memory $\begin{cases} \text{get} \\ \text{put} \end{cases}$
 $O(\log_{\frac{P}{2}} N)$ I/O $\begin{cases} \text{get} \\ \text{put} \end{cases}$

B+ Tree

With P records / key+pointer pairs per page:

get(k)

- $O(1)$ Memory complexity
- $O(\log_P(N))$ IO complexity
 - Contrast: $O(\log_2(N))$ in binary search

put(k, v)

- $O(1)$ Memory complexity
- $O(\log_P(N))$ IO complexity
 - $O(\log_P(N))$ reads
 - $O(\log_P(N))$ writes; $O(1)$ amortized writes

LSM Tree

Insight: Updating one record involves many redundant writes in a B+ Tree

Building Block: Sorted Run

- Originally: ISAM Index
- Now: Sorted Array + Fence Pointers (optional Bloom Filter)

LSM Tree

- In-Memory Buffer
- Level 1: B records
- Level 2: $2B$ records
- Level 3: $4B$ records
- Level i : $2^{i+1}B$ records

LSM Tree

put(k,v)

- Append to in-memory buffer.
- If buffer full, sort, and write sorted run to level 1.
- If level 1 already occupied, merge sorted runs and write result to level 2.
- If level 2 already occupied, merge sorted runs and write result to level 3.
- ...
- If level i already occupied, merge sorted runs and write result to level $i+1$.

LSM Tree

get(k,v)

- Linear scan for k over in-memory buffer.
- If not found, look up k in level 1.
- If not found, look up k in level 2.
- ...

LSM Tree

update(k,v)

- exactly as **put**
- ... but when merging sorted runs, if both input runs contain a key, only keep the newer copy of the record.

delete(k)

- exactly as **update**, but write a 'tombstone' value.
- If **get** encounters a tombstone value, return "not found".
- When merging into lowest level, can delete tombstone.

$\beta - \epsilon$ Trees

Like B+ Tree, but directory pages contain a buffer.

- Writes go to the root page buffer.
- When the root page buffer is full, move its buffered writes to level 2 buffers.
- When a level 2 buffer is full, move its buffered writes to level 3 buffers.
- ...
- When the last directory level buffer is full, apply the writes to the relevant leaves.

Set

- **add(k)**: Updates the set.
- **test(k)**: Returns true iff **add(k)** was called on the set.

Lossy Set

- **add(k)**: Updates the set.
- **test(k)**:
 - Always returns true if **add(k)** was called on the set.
 - Usually returns false if **add(k)** was not called on the set.

Bloom Filters

- A specific implementation of a lossy set.
- $O(N)$ memory to store N keys with a fixed false-positive rate.
 - ... but with a very small constant (1 byte per key $\approx 1 - 2\%$ false positive rate).

Bloom Filters

Before

- Read file
- Find and return record for key

After

- If in-memory bloom filter returns false, return not-found
- Read file
- Find and return record for key